Barrett™
ADVANCED ROBOTICS

Low Active Power: 50 W
Reach: 1 m
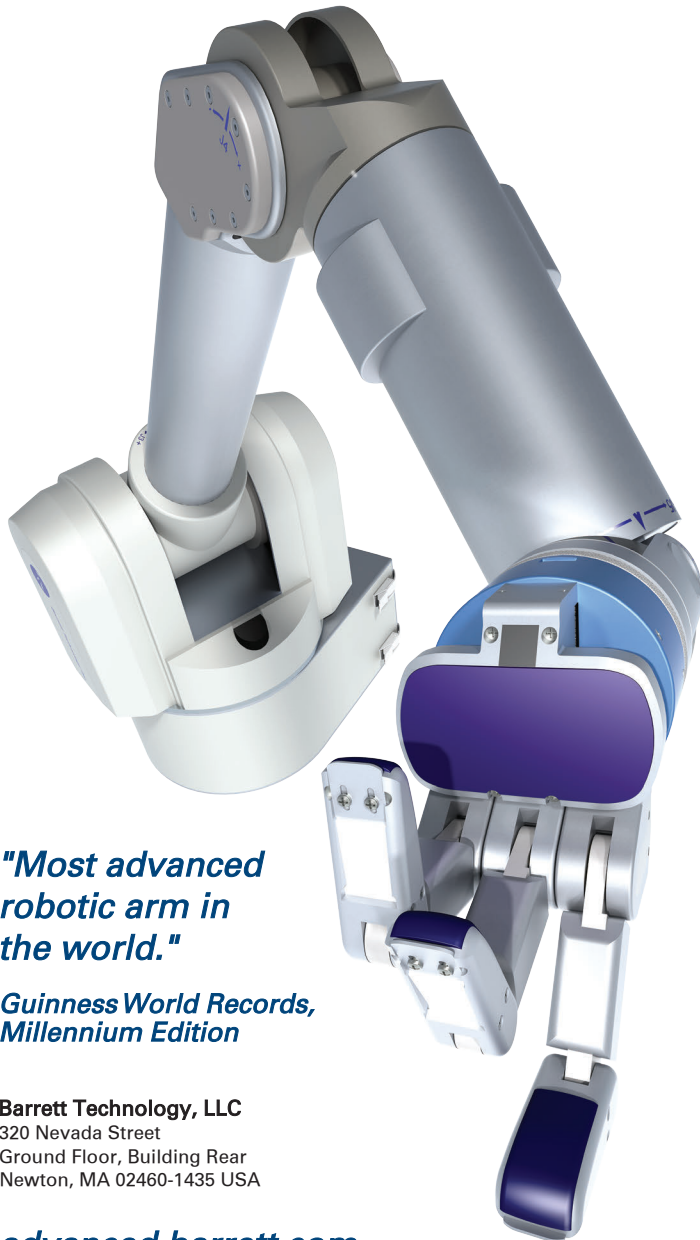
WAM™ Arm

Force-controllable robotic arm

The WAM™ Arm is a highly dexterous backdrivable manipulator. It is the only commercially available robotic arm with direct-drive capability supported by Transparent Dynamics™ between the motors and joints, so its joint-torque control is unmatched and guaranteed stable. It is built to outperform today's conventional robots by offering extraordinary dexterity, zero backlash, and near-zero friction.

The WAM™ Arm is available in 3 main configurations, 4-DOF, 7-DOF, and 4-DOF with 3-DOF Gimbals (DOF = degrees of freedom). The joint ranges exceed those for conventional robotic arms.

All axes are driven by high-performance brushless motors which use space-vector electronic commutation for the smoothest, most precise motions in both position and force control. Since the joints are highly backdrivable, true dynamic controls can be applied, resulting in much higher performance than is achievable with conventional manipulators. The high backdriveability enables inherent force-control, haptics, hybrid control, and teleoperation.

With its advanced cabled differential and patented cable auto-tensioners, the WAM™ Arm is the ideal platform for implementing Whole-Arm Manipulation (WAM) techniques.

To operate in and around obstacles in the workspace, the arm link surfaces are simple, smooth, and slender to prevent task interference.

Combined with Whole-Arm force sensing, the WAM™ can manipulate large, heavy objects with the sides of its links as well as smaller objects with an attached grasper, such as the BarrettHand (shown left). Furthermore, the WAM™ Arm will operate with industrial grippers, end of arm tooling, and tool changers.

No hassle, open-source software

The WAM™ Arm software enhances the customer's ability to exploit the dynamic capabilities, key concepts and features, and extensive possibilities associated with the WAM™ Arm. Some of the highlighted features include "Teach and Play", force control, and gravity compensation.

The Teach-and-Play software allows the user, including non-programmers, to record trajectories manually and play the same trajectories back at different speeds and accelerations with the touch of a key.

Force control of the robot in Cartesian space is as easy as calling a single high-level force function. If you prefer to have low-level control of the motor torques, the WAM™ hd[i l Vq̄ ¯a̅W̄g̅m also exposes the raw torque output functions which form the basis of the higher-level control.

The WAM™ Arm's zero-gravity compensation permits the user to move the WAM™ Arm in a floating motion through any trajectory.
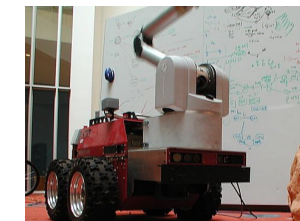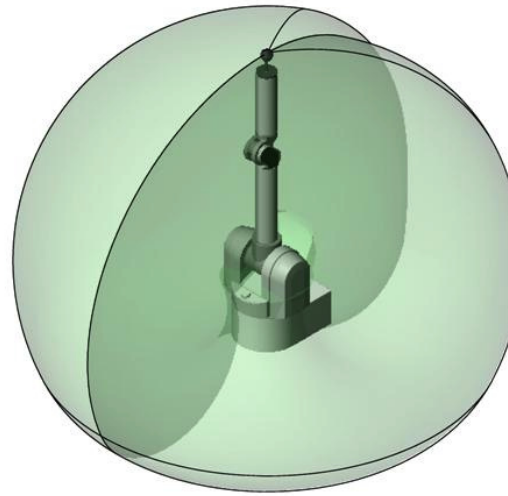
"Most advanced robotic arm in the world."

Guinness World Records, Millennium Edition

Barrett Technology, LLC
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advanced.barrett.com

Features

- No controller cabinet
- Low power
- Cartesian force control
- AC or DC operation
- Gravity compensation
- Silent operation
- Human-like kinematics
- Highest performance space-vector commutation
- Brushless motors

- Open-source C++ control software
- ROS and ROS2 libraries
- 1-kHz motor torque control
- Field-upgradeable firmware
- Direct-teach recording without force sensor, with or without motor power
- 6-wire bus (4 power, 2 communication)
- High speed/payload options available
- Auxiliary I/O and signal pass-through
- Joints never locked, for safety

Applications

Mobile Platform Robotics

Whole Arm Haptics Medical Rehabilitation

WAM Specifications

Power Requirement	Minimum	50 watts
Voltage Requirement	AC (mains)	100-240VAC 1φ, 50-60 Hz
	DC (mobile)	24-80VDC
	Ultra High Speed	48-160VDC
Reach		1000 mm
Payload	4-DOF	4 kg / 8 kg
(Standard / High Payload)	7-DOF	3 kg / 6 kg
Peak Endtip Velocity	Standard	3 m/s
	High Speed	5 m/s
	Ultra High Speed	15 m/s
Mass of robot	4-DOF	25 kg
	7-DOF	27 kg
Work volume		3.5 m^3
Repeatability	4-DOF	1000 μm / 100 μm
(Standard / High Precision)	7-DOF	2000 μm / 200 μm
Mechanical stiffness		1.5x10^6 N/m
Control stiffness		5000 N/m

Go to **advanced.barrett.com** for complete specifications
TECHNICAL SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE

Workspace, Isometric View

The Barrett WAM™ has a generally spherical workspace approximately 2 meters in diameter.
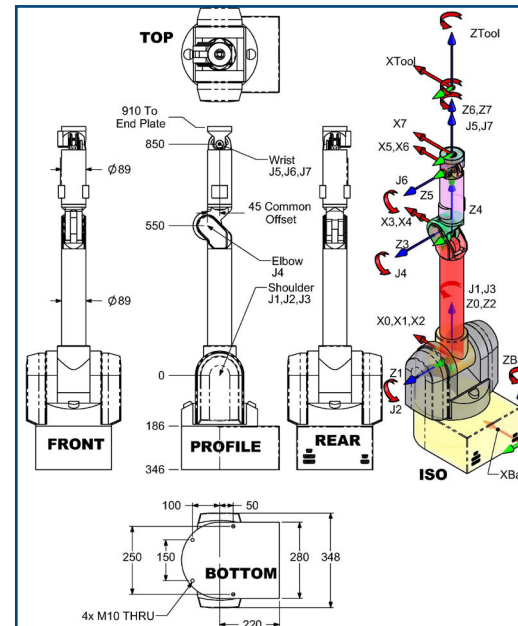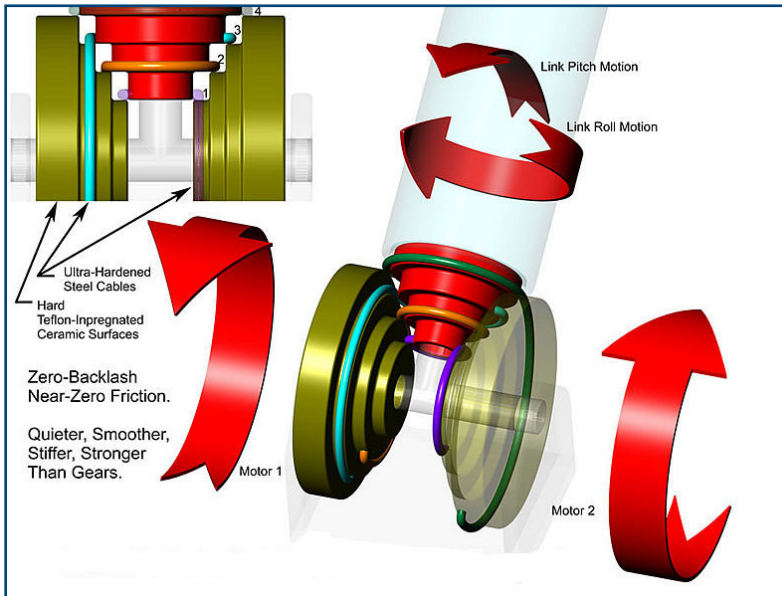

Barrett's Gearless Transmissions

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