

Zero Calibration Procedure

For 4-DOF and 7-DOF WAM Arms
running libbarrett versions 1.0.0 or newer.

Barrett Technology, Inc.
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From a terminal, run the following command:

```
robot@wampc:~$ bt-wam-zerocal
```

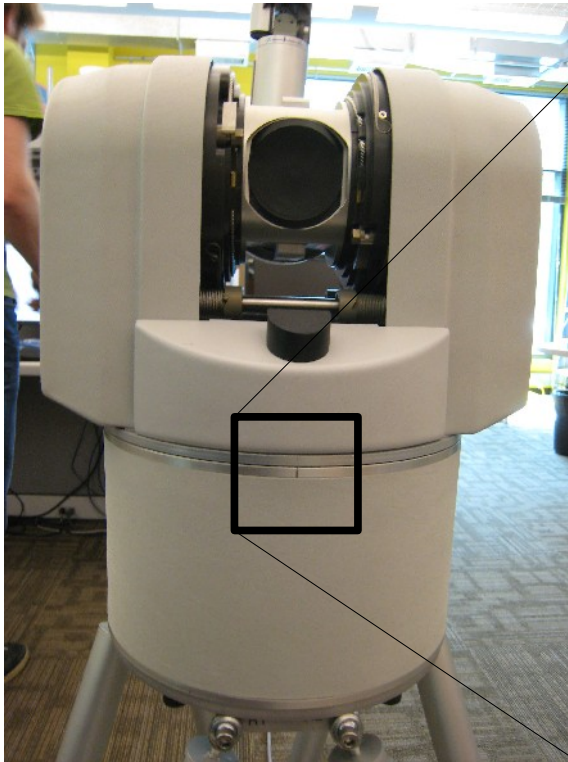
... then follow the on screen instructions. Use the following pictures as a reference.

Standard home position

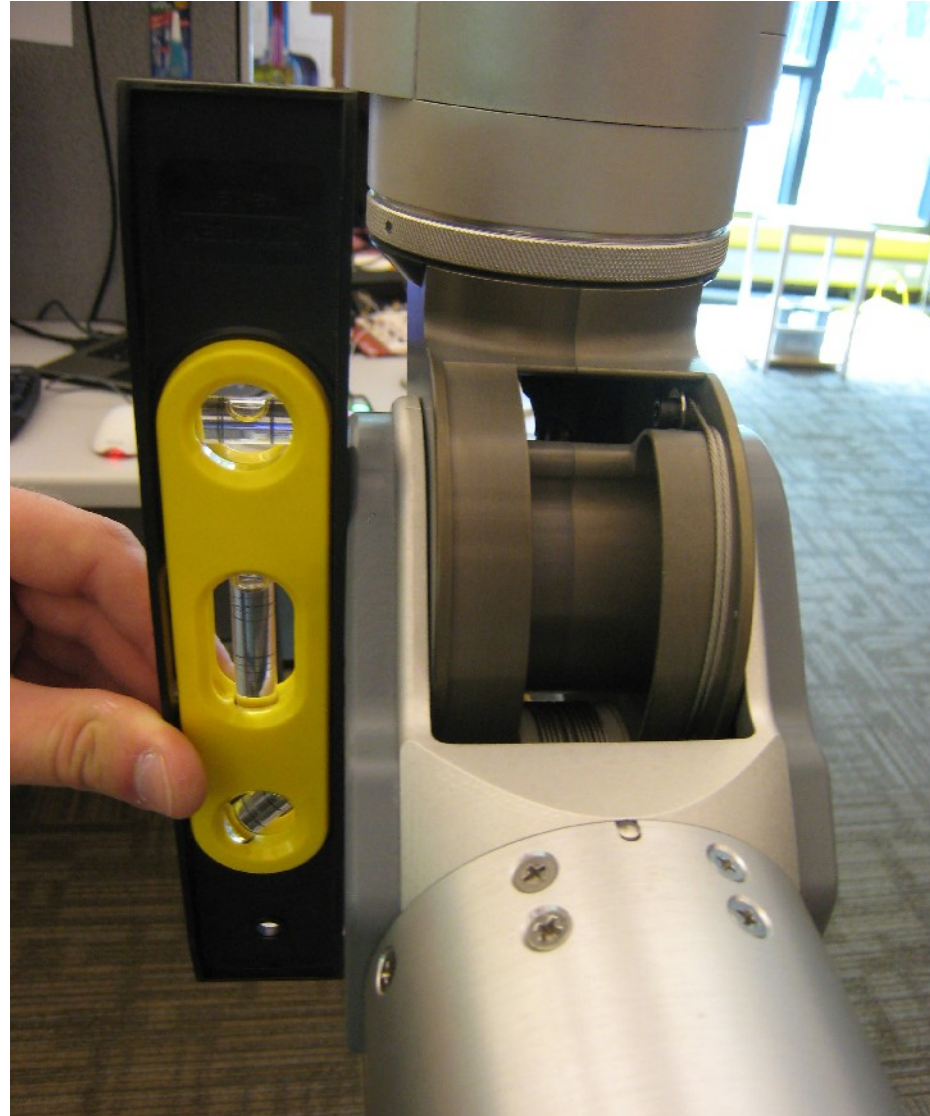


Motor 7 is on the
same side as Motor 6

Joint 1



Joint 3



Joint 2



Joint 4

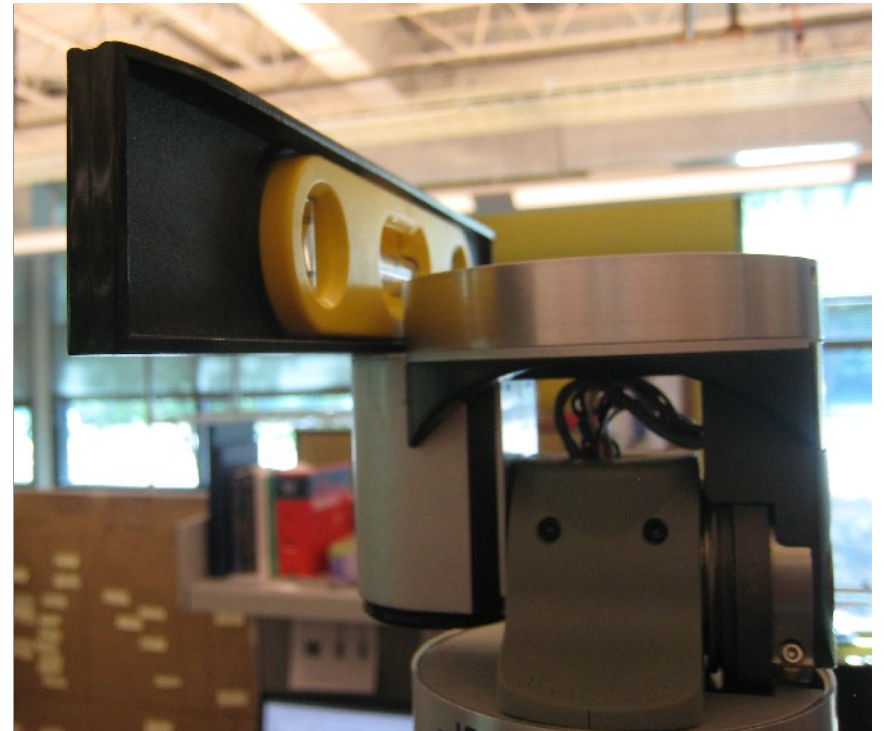


Joint 6

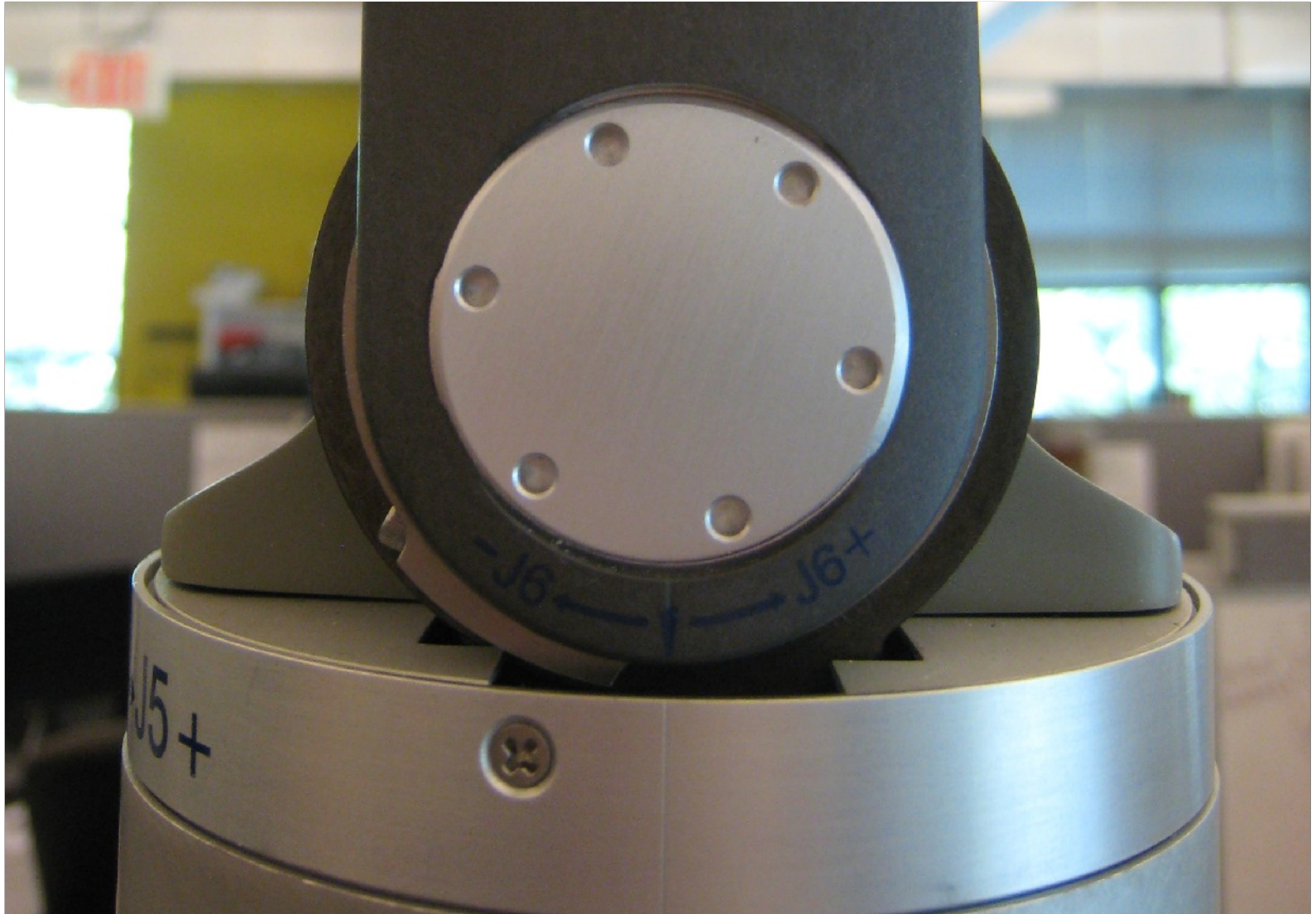
Preferred method



Alternative method



Joint 5



Joint 7

